## Contents

Ce	ertifi	cate			iii
De	eclar	ation by the Candidate			v
Co	opyri	ght Transfer Certificate			vii
Ac	knov	wledgements			ix
Co	onter	nts			xiii
Lis	List of Figures xvii			xvii	
Lis	List of Tables xix				xix
Ał	Abbreviations xxi				xxi
$\mathbf{S}\mathbf{y}$	Symbols  xxv				
Pr	efac	e		XX	xvii
1	<b>Intr</b> 1.1 1.2 1.3 1.4 1.5	<b>roduction</b> Need of Safety Analysis for Safety Critical Systems (SCSs)      History of Safety      Motivation and Objectives of Research      Scope of Research      Thesis Outline	· · · ·	· ·	<b>1</b> 7 9 10 12 12
2	<b>Pre</b> 2.1	liminaries Dependability			<b>17</b> 18

		2.1.1	The Threats: Faults, Errors, and Failures	20
		2.1.2	The Attributes of Dependability	22
		2.1.3 The Means to Attain Dependability		22
	2.2	Classi	fication of Computer Based System	23
	2.3		Dependability Mathematics	24
		2.3.1	Concepts of Probability Theory	24
		2.3.2	Time to Failure, Reliability, Hazard rate and their relations .	27
		2.3.3	Probability Distributions Used in Safety Studies	29
	2.4	Deper	dability Attribute Prediction Metrics	33
		2.4.1	Failure Rate	34
		2.4.2	Mean Time to Failure	36
		2.4.3	Mean Time to Repair	37
		2.4.4	Availability and Average Availability	37
		2.4.5	Some other important metrics	38
	2.5	State	Space Model and Related Concepts	39
		2.5.1	State Machines	39
		2.5.2	Unified modeling Language (UML)	42
		2.5.3	Markov Model	50
		2.5.4	Petri Net	58
	2.6	Concl	usion $\ldots$	63
3	Rel	iability	and Safety: State-of-the-art and Perspectives	65
3		•	v and Safety: State-of-the-art and Perspectives	<b>65</b> 66
3	3.1	Introd	$\mathbf{uction}$	66
3	$3.1 \\ 3.2$	Introd Relia	luction	66 68
3	3.1	Introd Relia A Cas	uction    . <td>66 68 73</td>	66 68 73
3	$3.1 \\ 3.2$	Introd Relia A Cas 3.3.1	uction    . <td>66 68 73 74</td>	66 68 73 74
3	$3.1 \\ 3.2$	Introd Relia A Cas 3.3.1 3.3.2	luction    . </td <td>66 68 73 74 74</td>	66 68 73 74 74
3	$3.1 \\ 3.2$	Introd Relia A Cas 3.3.1	uction    . <td>66 68 73 74 74 75</td>	66 68 73 74 74 75
3	$3.1 \\ 3.2$	Introd Relia A Cas 3.3.1 3.3.2 3.3.3 3.3.4	luction	66 68 73 74 74
3	3.1 3.2 3.3	Introd Relia A Cas 3.3.1 3.3.2 3.3.3 3.3.4 Reliat	Juction	66 68 73 74 74 75
3	3.1 3.2 3.3	Introd Relia A Cas 3.3.1 3.3.2 3.3.3 3.3.4 Reliat	Juction	66 68 73 74 74 75 75
3	3.1 3.2 3.3	Introd Relia A Cas 3.3.1 3.3.2 3.3.3 3.3.4 Reliat and P	Juction	66 68 73 74 74 75 75 75
3	3.1 3.2 3.3	Introd Relia A Cas 3.3.1 3.3.2 3.3.3 3.3.4 Reliat and P 3.4.1	Juction	66 68 73 74 74 75 75 75
3	3.1 3.2 3.3	Introd Relia A Cas 3.3.1 3.3.2 3.3.3 3.3.4 Reliat and P 3.4.1	Juction	66 68 73 74 74 75 75 75 77 78
3	3.1 3.2 3.3	Introd Relia A Cas 3.3.1 3.3.2 3.3.3 3.3.4 Reliab and P 3.4.1 3.4.2	Juction	66 68 73 74 74 75 75 75 77 78 78
3	3.1 3.2 3.3	Introd Relia A Cas 3.3.1 3.3.2 3.3.3 3.3.4 Reliab and P 3.4.1 3.4.2 3.4.3	Juction	666 688 73 74 74 75 75 75 75 77 78 78 78 78
3	3.1 3.2 3.3	Introd Relia A Cas 3.3.1 3.3.2 3.3.3 3.3.4 Reliab and P 3.4.1 3.4.2 3.4.3 3.4.4	Juction	666 688 73 74 74 75 75 75 77 78 78 78 78 80
3	3.1 3.2 3.3	Introd Relia A Cas 3.3.1 3.3.2 3.3.3 3.3.4 Reliab and P 3.4.1 3.4.2 3.4.3 3.4.4 3.4.5	Juction	666 688 73 74 74 75 75 75 77 78 78 78 78 80
3	3.1 3.2 3.3	Introd Relia A Cas 3.3.1 3.3.2 3.3.3 3.3.4 Reliab and P 3.4.1 3.4.2 3.4.3 3.4.4 3.4.5	Juction	666 688 73 74 74 75 75 75 77 78 78 78 78 78 80 80
3	3.1 3.2 3.3	Introd Relia A Cas 3.3.1 3.3.2 3.3.3 3.3.4 Reliat and P 3.4.1 3.4.2 3.4.3 3.4.4 3.4.5 3.4.6	Juction	666 688 73 74 74 75 75 75 77 78 78 78 78 78 80 80 80

		3.4.10 Phase 2.B and its sub phases: Reliability prediction for interfaces 8	2		
		3.4.11 Phase 2.C and its sub phases: Reliability prediction for			
		hardware system	2		
		3.4.12 Phase 3: Overall reliability prediction for SCCS 8	2		
		3.4.13 Phase 4: Experimental Validation	3		
	3.5	Safety Prediction: State-of-the-art and Perspectives	3		
	3.6	Limitations of existing approaches	2		
		3.6.1 Modeling Limitations	2		
		3.6.2 Analysis Limitations	3		
		3.6.3 Parameter Estimation Limitations	4		
		3.6.4 Validation Limitations	4		
		3.6.5 Optimization Limitations	5		
	3.7	Conclusion $\ldots \ldots 15$	5		
4	$\mathbf{Pro}$	blem Formulation and Solution Strategies 15	9		
	4.1	Introduction	0		
	4.2	Problem Formulation	3		
		4.2.1 Difficulty in generalization of the quantitative safety analysis			
		methodology	3		
		4.2.2 Uncertainty in State-space models	5		
	4.3	Solution Strategies	5		
		4.3.1 Strategy for dealing with the difficulty in generalization of the			
		quantitative safety analysis methodology	6		
		4.3.2 Strategy for dealing with the uncertainty in State-space safety			
		models $\ldots$	7		
	4.4	Conclusion	8		
<b>5</b>	A	Probabilistic Hazard Assessment Framework for the Safety			
	Crit	tical and control System 16	9		
	5.1	Introduction	0		
	5.2	Related Work			
	5.3	3 The Proposed Method for Quantification of Hazards with a Case			
		Study Illustration			
		5.3.1 Phase 1: Develop State Machine Model of the System 17	5		
		5.3.2 Phase 2: Identify Possible Failures from State Transition			
		Diagram	6		
		5.3.3 Phase 3: Identify Possible Failures from State Transition			
		Diagram $\ldots \ldots 17$	6		
		5.3.4 Phase 4: Map Failure Rate to All Identified Hazards Based on			
		SIL (IEC 61508)			
		5.3.5 Phase 5: Expand State Machine with Failure Rate 17	9		

		5.3.6 Phase 6: Convert the State Machine into CTMC Model and	101
		Assessment of Hazard Probability	
	5.4	Experimental Validation	
	5.5	Conclusion	187
6	Tra	nsformation of Deterministic Models into State space Models	
		Safety analysis of safety Critical Systems: A Case Study of	
			89
	6.1	Introduction	190
	6.2	Related Work	191
	6.3	A Case Study	194
		6.3.1 RCICS Overview	194
		6.3.2 RCICS Operation and Operating Modes	196
	6.4	The Proposed Method For Safety Analysis By Use Of Conversion The	
		UML Model into Petri Net Model with A Case Study Illustration 1	197
		6.4.1 Phase 1: Requirements Analysis	197
		6.4.2 Phase 2: Identification of Possible Failures	198
		6.4.3 Phase 3: Formulation of USCD	200
		6.4.4 Phase 4: Validation of USCD	201
		6.4.5 Phase 5: Generation of PN Model from USCD	201
		6.4.6 Phase 6: Analysis Methodology Validation	203
	6.5	Conclusions	212
7	Cor	clusion and Future Research 2	215
	7.1	Difficulty in Generalizing the Quantitative Safety Analysis	
		Methodology	216
	7.2	Uncertainty in State space Models	217
	7.3	Future Work .	218
Bi	iblio	graphy 2	219
		<b>-</b>	

Α	List of Publications	237
---	----------------------	-----

## PREFACE

A safety-critical system executes the critical tasks, the failure of which may jeopardize human life, lead to considerable financial misfortune, or cause extensive Therefore, safety is considered as one of the most environmental damage. critical areas of research, while dealing with safety-critical systems. Traditional safety-critical systems are being converted into digital systems for several benefits. To support various features of a safety-critical system, the digital systems are becoming more complex in functional behaviors. Complex digital systems comprised of many software and hardware components mostly of them are heterogeneous A safety-critical system comprises of a large no. of heterogeneous in nature. components, there is higher risk always associated with the safety-critical systems due to possible failures in Hardware/Software involved there in. Several techniques are available to perform the safety analysis of such systems. An extensive literature survey was carried out to identify the available methods for safety analysis of safety-critical digital systems. Most of them works on qualitative assessment rather than quantitative assessment. However, quantitative assessment has several benefits over qualitative assessment such as -(i) risks are sorted by their adversity impact, and (ii) security levels can be better determined/defined through consideration of three elements that are availability, integrity, and confidentiality. Further, safety analysis during the early phases of system development life cycle has many significant benefits such as – (i) help in taking decisions to select most suitable design (ii) cost minimization (iii) analyzing the sensitivity of the system safety to its component safety (iv)identify safety bottlenecks. The proposed work deals with a new probabilistic approach to quantify safety of safety-critical systems during the design phase of the systems that is based on the probabilistic safety assessment to deal with the shortcomings of the existing techniques using state-space models.

Further, it is a challenging task to capture all the requirements including safety requirements through state space models. Also, verifying that the constructed model has captured all the requirements is again a problem in itself, because of all the understanding of stakeholders may not get captured during development of the state-space model. Failing to model all the requirements will give inaccurate safety assessment. UML is a well-known and successful way of modelling which is used for specifying requirements. UML can capture all the requirements and be easily understood by all the stakeholders. This motivates us to propose a methodology to convert the UML model into a state space model that can be used for quantitative assessment of a safety-critical systems under consideration. A framework is proposed and introduced in this thesis to transform UML model into a state-space model in the form of a Petri net, which is a reliable graphical and mathematical tool to perform several static and dynamic analysis.

All the above proposed approaches are validated considering a real-time safety-critical system of Nuclear Power Plant along with some noticeable findings.