

Contents

Abstract	v
List of Figures	xi
Nomenclature	xiii
1 Introduction	1
1.1 Background	1
1.2 Dynamical system	3
1.3 Classification of systems with disturbance	4
1.3.1 Systems with vanishing and non vanishing disturbance	5
1.3.2 Systems with matched and unmatched disturbance	5
1.4 Classification of systems with time-delay	5
1.4.1 Systems with discrete delays	6
1.4.2 Systems with distributed delays	6
1.4.3 Neutral delay systems	6
1.5 Lyapunov stability Definitions and Theorems	7
1.5.1 Stability definition for system without delay	7
1.5.2 Stability Definitions for system with delay	8
1.5.3 Lyapunov stability theorem	9
1.5.4 Lyapunov-Razumikhin Theorem	9
1.5.5 Lyapunov-Krasovskii Theorem	10
1.6 Literature Review on stability analysis	10
1.6.1 Literature Review on Lyapunov direct method	11
1.6.2 Literature Review on Lyapunov-Razumikhin Method	13
1.6.3 Literature Review on Lyapunov-Krasovskii method	14

1.7	Literature survey on controller design	16
1.7.1	Sliding Mode Control	16
1.7.2	Proportional and Integral Control	17
1.7.3	Observer based Controller Design	18
1.8	Motivation	19
1.9	Thesis Objectives	21
1.10	Organization of the Thesis	22
2	Nonsmooth PI Controller for Uncertain Systems	25
2.1	Introduction	25
2.2	Notions and Preliminaries	28
2.3	Background and Problem Formulation	29
2.4	Main Results	30
2.4.1	Nonsmooth PI for the First Order System for $n = 1$ in (1.3):	30
2.4.2	Nonsmooth PI for the Higher Order Uncertain Chain of Integrators	31
2.5	Construction of Lyapunov Function and Proof of Main Theorems	32
2.5.1	Proof of Theorem 2	35
2.6	Simulation	39
2.7	Summary	40
3	Artificial Delayed Output Twisting Algorithm	43
3.1	Introduction	43
3.2	Notions	44
3.3	Main Results	45
3.4	Applications	51
3.4.1	Controller Design for Second Order System	52
3.4.2	Mitigation of unmatched disturbance	52
3.4.3	Observer Design	53
3.5	Simulation	53
3.6	Summary	54
4	New Lyapunov-Krasovskii functional for Stability Analysis of Time-delay System	55

4.1	Introduction	55
4.2	System Description and Preliminaries	56
4.3	Main Results	58
4.4	Illustrative examples	63
4.5	Summary	65
5	Stability Criteria based on First and second order polynomials	67
5.1	Introduction	67
5.2	Useful Lemmas	69
5.3	Main Results	71
5.3.1	Lyapunov-Krasovskii functional	71
5.3.2	Zero-equalities	72
5.3.3	Stability Analysis	73
5.4	Numerical Examples	79
5.4.1	System Parameters	79
5.4.2	Comparative results	79
5.4.3	Simulation verification	81
5.5	Summary	83
6	Stability analysis of delayed neural network using new delay-product based functionals	85
6.1	Introduction	85
6.2	System Description and Preliminaries	87
6.3	Main Results	88
6.3.1	New delay-product type functionals	88
6.3.2	Stability analysis	89
6.4	Numerical Analysis	96
6.4.1	Examples	96
6.4.2	Performance comparison	98
6.5	Summary	101
7	Conclusions and suggestions for future work	103
7.1	Research summary	103

7.2	Thesis Contributions	103
7.3	Suggestions for future work	104

List of Figures

2.1	Evolution of position with respect to time	41
2.2	Evolution of control with respect to time	41
3.1	Evolution of states in presence of time-varying disturbance	54
5.1	State responses of Example 1	82
5.2	State responses of Example 2	83
5.3	State responses of Example 3	83