

# Table of Contents

	<b>Page No.</b>
<b>Acknowledgements</b>	i-ii
<b>Abstract</b>	iii-v
<b>List of Figures</b>	vi-viii
<b>List of Tables</b>	ix
<b>List Of Symbols And Abbreviations</b>	x-xv
<b>1 Introduction</b>	<b>1-25</b>
<b>1.1 Motivation</b>	1
<b>1.2 Contribution of The Thesis</b>	3
<b>1.3 Organization Of The Thesis</b>	5
<b>1.4 Literature Survey</b>	7
1.4.1 Buck Regulator	7
1.4.2 Integer Order PID Controller	8
1.4.3 Fractional Order Control	11
<b>2 Basic Ideas of Fractional Calculus</b>	<b>26-39</b>
<b>2.1 Integer Order Calculus</b>	28
<b>2.2 Riemann-Liouville Definition of Fractional calculus</b>	31
2.2.1 Fractional Order Integral	31

2.2.2	Fractional Order Derivative	32
<b>2.3</b>	<b>Caputo Definition Of Fractional Calculus</b>	34
<b>2.4</b>	<b>Grünwald–Letnikov Definition Of Fractional Calculus</b>	35
<b>2.5</b>	<b>Riemann-Liouville Fractional Definition For Complex Order Calculus</b>	36
<b>2.6</b>	<b>Laplace Transform Of Fractional Calculus</b>	37
2.6.1	Laplace Transform Of Riemann-Liouville Definition	37
2.6.2	Laplace Transform Of Caputo Definition	38
2.6.3	Laplace Transform Of Grünwald–Letnikov Definition	38
<b>2.7</b>	<b>Conclusion</b>	39
<b>3</b>	<b>Design and Analysis of Existing Fractional Order Controllers</b>	<b>40-59</b>
<b>3.1</b>	<b>First Generation CRONE Controller</b>	43
3.1.1	Illustrative Example	44
<b>3.2</b>	<b>Second Generation CRONE Controller</b>	46
3.2.1	Illustrative Example	48
<b>3.3</b>	<b>Third Generation CRONE Controller</b>	50
3.3.1	Illustrative Example	52
<b>3.4</b>	<b>Fractional Order Lead-Lag Controller</b>	54
3.4.1	Illustrative Example	56
<b>3.5</b>	<b>Conclusion</b>	58
<b>4</b>	<b>Improved Analytical Design of Fractional Order PI Controller for Non-Monotonic Phase Systems</b>	<b>60-75</b>
<b>4.1</b>	<b>Object Of Study</b>	62
<b>4.2</b>	<b>Proposed Method</b>	64
<b>4.3</b>	<b>Designing Of The FOPI And IOPID Controller</b>	67
<b>4.4</b>	<b>Results</b>	70
<b>4.5</b>	<b>Conclusion</b>	75

<b>5</b>	<b>Design of Fractional Order PD Controller for Non-Monotonic Phase System</b>	<b>76-92</b>
5.1	System Modeling	79
5.2	Basic Ideas of Fractional order PD Controller and its Design Specifications	81
5.3	Proposed Technique	83
5.3.1	Compensation Methodology	83
5.3.2	Fractional Order Proportional Derivative Controller	85
5.4	Illustrative Example	88
5.5	Conclusion	92
<b>6</b>	<b>Frequency Domain Based Fractional Order Proportional Integral Derivative controller For Process Control Systems</b>	<b>93-117</b>
6.1	The design problem formulation of Fractional Order Proportional Integral Derivative Controller	97
6.2	Design Of Fractional Order Proportional Integral Derivative Controller	99
6.2.1	Non-Linear Minimization Problem	100
6.3	Illustrative Example-I	101
6.3.1	Results	103
	6.3.1.1 Step Response Of Closed Loop System	103
	6.3.1.2 Open Loop Frequency Response	104
	6.3.1.3 Sensitivity Function	105
	6.3.1.4 Complementary Sensitivity Function	106
6.4	Illustrative Example-II	109
6.4.1	Results	111
	6.4.1.1 Step Response Of Closed Loop System	111
	6.4.1.2 Open Loop Frequency Response	112
	6.4.1.3 Sensitivity Function	113
	6.4.1.4 Complementary Sensitivity Function	114
6.5	Conclusion	116

<b>7</b>	<b>Design of Fractional Order Phase Shaper</b>	<b>118-132</b>
7.1	Modeling of Fractional Order Phase Shaper	121
7.1.1	Assumptions To Be Made In Design Process	121
7.1.2	Non-Linear Minimization Problem	124
7.2	Illustrative Example-I	125
7.3	Illustrative Example-II	128
7.4	Conclusion	131
<b>8</b>	<b>Conclusions and Future Perspectives</b>	<b>133-137</b>
8.1	Conclusions	134
8.2	Future Scope of Work	137
	<b>References</b>	<b>138</b>
	<b>Appendix</b>	<b>153</b>
	<b>List of Publications</b>	<b>162</b>