

## **CERTIFICATE**

---

It is certified that the work contained in the thesis titled “**Finite Deformation Analysis of Crack Tip Fields in Plastically Compressible Hardening-Softening-Hardening Solids**” by **Shushant Singh** has been carried out under our supervision and that this work has not been submitted elsewhere for a degree.

It is further certified that the student has fulfilled all the requirements of Comprehensive Examination, Candidacy and SOTA for the award of Ph.D. Degree.

**Dr. Debashis Khan**  
(Supervisor)  
Associate Professor  
Dept. of Mechanical Engineering  
Indian Institute of Technology (BHU)  
Varanasi-221005

**Prof. S.K.Panda**  
(Co-Supervisor)  
Professor  
Dept. of Mechanical Engineering  
Indian Institute of Technology (BHU)  
Varanasi-221005

## DECLARATION BY THE CANDIDATE

---

I, **Shushant Singh**, certify that the work embodied in this thesis is my own bonafide work and carried out by me under the supervisions of **Dr. Debashis Khan** and **Prof. S.K. Panda** from July 2013 to July 2018, at the Department of Mechanical Engineering, Indian Institute of Technology (BHU) Varanasi. The matter embodied in this thesis has not been submitted for the award of any other degree/diploma. I declare that I have faithfully acknowledged and given credits to the research workers wherever their works have been cited in my work in this thesis. I further declare that I have not wilfully copied any other's work, paragraphs, text, data, results, etc., reported in journals, books, magazines, reports, dissertations, theses, etc., or available at websites and have not included them in this thesis and have not cited as my own work.

**Date:**

**Place:** IIT (BHU) Varanasi

**(Shushant Singh)**

## CERTIFICATE BY THE SUPERVISORS

It is certified that the above statement made by the student is correct to the best of our knowledge.

**Dr. Debashis Khan**  
(Supervisor)  
Associate Professor

**Prof. S.K. Panda**  
(Co-Supervisor)  
Professor

**Prof. S.K. Sinha**  
Head of Department  
Dept. of Mechanical Engineering  
Indian Institute of Technology (BHU)  
Varanasi-221005

## **COPYRIGHT TRANSFER CERTIFICATE**

---

**Title of the Thesis:**     **Finite Deformation Analysis of Crack Tip Fields in Plastically  
Compressible Hardening-Softening-Hardening Solids**

**Name of the Student:** **Shushant Singh**

### **Copyright Transfer**

The undersigned hereby assigns to the Indian Institute of Technology (Banaras Hindu University) Varanasi all rights under copyright that may exist in and for the above thesis submitted for the award of the **Doctor of Philosophy**.

**Date:**

**Place:** IIT (BHU) Varanasi

**(Shushant Singh)**

**Note:** However, the author may reproduce or authorize others to reproduce material extracted verbatim from the thesis or derivative of the thesis for author's personal use provided that the source and the Institute's copyright notice are indicated.

## DEDICATION

---

This thesis is dedicated to

Lord *Sri Krishna*

ॐ पूर्णमदः पूर्णमिदं पूर्णात्पूर्णमुदच्यते।

पूर्णस्य पूर्णमादाय पूर्णमेवावशिष्यते ॥

Sri Isopanishad

The Personality of Godhead is perfect and complete. And because He is completely perfect, all emanations from Him, such as this phenomenal world, are perfectly equipped as a complete whole. Whatever is produced of the complete whole is also complete by itself. And because He is the Complete Whole, even though so many complete units emanate from Him, He remains the complete balance.

## ACKNOWLEDGEMENTS

---

At the outset, let me pay my obeisance to Lord Krishna for catapulting me to this level of academic pursuit. Thereafter, let me express my sincere gratitude to my respected supervisors - Dr. Debashis Khan and Prof. S.K. Panda for their matured guidance, invaluable encouragement, moral support, friendship, providing enough space to work over the past five years. I owe them much for all of their superior guidance over the years.

I wish to acknowledge my sincere gratefulness to Prof. S.K. Sinha, Head, Department of Mechanical Engineering, Indian Institute of Technology (BHU), Varanasi, the previous heads Prof. A.K. Jha, Prof. A.K. Agrawal, and Prof. V.P. Singh for their kind gesture and extending all sorts of facilities in the department to pursue this kind of research work.

I would like to express my grateful thanks to my RPEC members Prof. Rajesh Kumar and Prof. P. Maiti for being part of my Ph.D. Committee and for being kind enough to make evaluation of my work-progress, extend meaningful comments and fruitful suggestions from time to time.

I am deeply indebted to Prof. Sandeep Kumar, for his help, spiritual values, precious advice and for the patience shown in our long and useful discussions. I would like to extend special thanks Prof. A.P. Harsha for his invaluable support, insightful conversations and continuous encouragement. My sincere thanks also go to Ministry of Human Resource Development, Govt. of India, for providing me financial assistance during my research tenure.

I am also thankful to Convener DPGC, Prof. Rajesh Kumar, previous Conveners Prof. A.P. Harsha, Prof. K.S. Tripathi, Prof. Sandeep Kumar and all respected DPGC members for their kind support.

I express my sincere thanks to the technical and office staff, especially Mr. S.P. Singh, Mr. Dinesh Kumar, Mr. J.K. Sinha, Mr. Akash Mishra, who helped me in various ways during this research work. I would like to thank all other people who have provided a truly conducive environment to successfully carry out this research. I shall be failing in my duty if I do not put on record my sincere appreciation and thankfulness to my seniors, lab mates and friends; Mr. Ambuj Sharma, Mr. Bharat S. Patel, Mr. Khemraj Sahu, Mr. Avinash Ravi Raja, Mr. Pushkar Jha, Mr. Rajeev Nayan Gupta, Mr. Manvandra K. Singh, Mr Parshant Kumar, Mr. Ankit Sharma, Mr. Sunil Kumar, Mr. Harish Babu, Mr. Gaurav Gugliyani, Mr. Arun Kumar, Mr. Ashish Srivastava, Mr. Ravindra Prasad, Mr. Vivek Gupta, Mrs. Perna Mishra, Mr. Ashish Pareta. Mr. Hemant Nutiyal, Mr. Sooraj rawat, Mr. Homendra Kumar, Mr. Hemant Chaudhary, Mr. Amod Kashyap, Mr. Yash Mittal. My special thanks go to Mrs. Amrita Khan, for her help, spiritual values, and for providing me a family like atmosphere.

I have no words to express my indebtedness and gratitude to my parents, Mrs. Asha and Mr. Satendra Kumar for showering their affectionate love and all possible support during my research-endeavour. They have been a guiding force all through my life, and I could always try to measure up to their expectations. I further express my sincere thanks to my elder brothers, Mr. Sachin Singh and Dr. Prashant Singh for their constant motivation and support during all these periods and all through my life. Words at my command are not sufficient enough to express my feelings especially for my Sister Dolly Singh and for my sweet nieces Ananya, Yashi, Kashvi, nephew Subh their smiling face always rejuvenates me.

I would fail in my duty if I fail to express my deep sense of gratefulness and thankfulness to my love Chetna, for being a constant source of love, energy and ecstasy to make each day of my life brimmed with a wonderfully pleasant experience.

To all these people and to those unmentioned, my heartfelt thanks.

**Shushant Singh**

## ABSTRACT

---

Considering the potential applications of relatively new materials like toughened structural polymers, metallic foams, plastics, transformation toughened ceramics, vertically aligned carbon nanotubes (VACNTs) etc and their limited exploration till now, it appears that there is a need to investigate more about the behavior of such materials under a wide range of loadings. Even though the effect of plastic dilatancy is neglected in classical plasticity theory, the above materials exhibit plastic volume changes and/or pressure-sensitive flow strength. In a recent study, it has been observed that the deformation of the entangled arrays of carbon nanotubes or VACNTs follow elastic-viscoplastic constitutive relation which incorporates plastic compressibility, plastic non-normality and a hardening-softening-hardening type hardness function. These VACNTs have prospective uses in a variety of applications like viscoelastic energy absorption, compliant thermal interfaces, biomimetic dry adhesives etc and hence it is useful to develop a predictive framework for the mechanical behavior of VACNTs under a wide range of loadings. In this thesis work, finite element finite deformation quasistatic mode I plane strain small scale yielding analysis of crack tip blunting and near crack tip fields was carried out for plastically compressible solids exhibiting a variety of uniaxial stress – strain responses. In particular solids with hardening-softening-hardening responses as can occur for foams and VACNTs have been considered. The novelty of this model includes unique characteristics as mentioned earlier like the hardening-softening-hardening material response, strain rate-dependence, and plastically compressible solids with plastic non-normality.

As for localization studies it needs a finite strain description, using FORTRAN a finite element finite deformation code has been developed in this work for the simulation



purpose. A convected coordinate Lagrangian formulation of the field equations was used. Quasistatic deformation conditions have been assumed and the equilibrium equations were expressed through the virtual work principle. The plane strain calculations were carried out for a semicircular region with a blunt notch. Quadrilateral elements each comprised of four crossed constant strain triangular elements have been used for mesh generation. Such elements with a proper aspect ratio and orientation are extensively used to replicate localized deformation pattern at finite strains. The initial part of the investigation refers to crack tip blunting and field quantities analyses under monotonic load while in the next part studies were conducted for fatigue loading to find the key results of crack tip blunting and fields. Even though most of the results presented are for plastic normality condition, however for comparison purpose some results have also been illustrated for constitutive relations exhibit plastic non-normality. While to simulate fatigue crack growth by means of finite elements, different techniques have been proposed over the years, however, in this work the crack growth modelling strategy employed was crack tip blunting/ resharpening mechanism where it is assumed that the crack tip blunts during the maximum load and resharpening of the crack tip takes place under minimum load. The simulations attempt to explain some of the salient features, like crack tip opening displacement, crack tip advancement, plastic zone shape and size, equivalent plastic strain distribution, equivalent stress, and distribution of hydrostatic stress at near crack region. The influences of plastic compressibility, material softening, cyclic stress intensity factor range, load ratio, number of fatigue load cycles on the near tip deformation and stress-strain fields were studied.

Numerical results obtained from the quasistatic mode I plane strain analysis demonstrate that plastic compressibility is found to give an increased crack opening displacement for a given value of the applied loading. The plastic zone shape and size are found to depend

on the plastic compressibility. Even though, material softening does not have a significant effect on the plastic zone size and shape, however, the near crack tip stress and deformation fields depend sensitively on whether or not material softening occurs. The combination of softening or softening-hardening material response and plastic compressibility leads to major deviation in the near crack tip stress and deformation fields from those that prevail for a hardening material. Plastic compressibility coupled with a softening or softening hardening material response leads to localized deformation in front of the initial crack tip, which in turn affects the shape of the blunted crack tip. The present numerical calculations show that the convergence of the cyclic trajectories of CTOD to stable self similar loops and plastic crack growth depend significantly on cyclic stress intensity factor range, load ratio, number of fatigue load cycles.

**Keywords:** Finite Deformation, Mode I crack, Plasticity, Compressible Solids, Material Softening, Monotonic Loading, Fatigue Loading, Finite Element Method.

# TABLE OF CONTENTS

---

<b>Certificate</b>	ii
<b>Acknowledgments</b>	vi
<b>Abstract</b>	ix
<b>Table of Contents</b>	xii
<b>List of Figures</b>	xvii
<b>List of Abbreviations and Symbols</b>	xxvi
<b>Chapter-1 Introduction</b>	<b>1-14</b>
1.1 Background	1
1.2 Motivation for the Research	9
1.3 Objectives and Scope of Study	11
1.4 Organization of the Thesis	12
<b>Chapter-2 Literature Review</b>	<b>15-49</b>
2.1 Introduction	15
2.2 Linear Elastic Fracture Mechanics	16
2.2.1 Stress Intensity Factor	18
2.2.2 Energy Release Rate	20
2.2.3 Small Scale Yielding	21
2.3 Elastic Plastic Fracture Mechanics	21
2.3.1 The Path Independent $J$ integral	23
2.3.2 Crack Tip Opening Displacement	24
2.3.3 Relation Between $J$ and CTOD	26
2.3.4 Plastic Zone Shape	28
2.4 Fracture Mechanics of Pressure Sensitive Yielding Materials	29

2.4.1 Studies Based on Small Deformation Formulation	30
2.4.2 Studies Based on Large Deformation Formulation	32
2.5 Fracture Mechanics of Plastically Incompressible Materials: Crack Tip Blunting and Fields	34
2.6 Fracture Mechanics under Fatigue Loading	36
2.6.1 Studies Based on Small Deformation Formulation	37
2.6.2 Studies Based on Large Deformation Formulation	38
2.7 Fracture Mechanics of Elastic-Plastic Solids with Plastic Non-normality	39
2.8 Crack Growth Modeling Strategies	41
(a) Node Release Technique	41
(b) Extended Finite Element Method	42
(c) Cohesive Zone Model	42
(d) Crack Tip Blunting Model	43
2.9 Computational Methods in Fracture Mechanics	43
2.9.1 Methods of Stress Calculations	44
2.9.1.1 Analytical Methods	44
2.9.1.2 Numerical Methods	45
(a) Finite Difference Method	46
(b) Finite Element Method	46
(c) Boundary Element Method	47
(d) Meshless Method	48
2.10 Concluding Remarks	49
<b>Chapter-3 Finite Deformation Formulation</b>	<b>51-66</b>
3.1.Introduction	51
3.2 Continuum Mechanics	52

3.2.1 Kinematics of Deformation	52
3.2.1.1 Motion	53
3.2.1.2 The Deformation Gradient	54
3.2.1.3 Strain Measures	56
3.2.1.4 The Velocity Gradient	57
3.2.1.5 Stress Measures	57
3.2.1.6 The Rate Viewpoint	59
3.2.2 Fundamental/balance Laws	60
3.2.2.1 Conservation of Mass	60
3.2.2.2 Conservation of Linear Momentum	60
3.2.2.3 Conservation of Angular Momentum	61
3.3. Quasi-static Deformation Histories	61
3.3.1 Conservational Formulation	63
3.3.2. Convected Coordinate Formulation	64
3.4 Concluding Remarks	66
<b>Chapter-4 Constitutive Relationships</b>	<b>67-73</b>
4.1 Introduction	67
4.2 Constitutive Relations	68
4.3 Concluding Remarks	72
<b>Chapter-5 Numerical Procedures and Geometry Analysed</b>	<b>75-94</b>
5.1 Introduction	75
5.2 Description of Analyses	75
5.2.1 Problem Formulation	76
5.2.2 Rate Tangent Formulation	78
5.2.3 Finite Element Equations	81

5.2.4 Geometry Description	85
5.3 Finite Element Issues	87
5.3.1 Element Description	87
5.3.2 Mesh Generation	90
5.3.3 Material Model	91
5.3.4 Equation Solver and Solution Control Options	93
5.4 Concluding Remarks	93
<b>Chapter-6 Results and Discussion</b>	<b>95-170</b>
6.1 Introduction	95
6.2 Problem Definition with Boundary Conditions	96
6.2.1 Boundary Conditions for Monotonic Loading	96
6.2.2 Boundary Conditions for Cyclic Loading	97
6.3 Convergence Studies	99
6.3.1 Mess Convergence	99
6.3.2 Program Verification Analysis	102
6.4 Some Results under Monotonic Loading (Plastic Normality Condition)	104
6.4.1 Applied $J$ versus Crack Tip Opening Displacement	104
6.4.2 Plastic Zone Shape and Size	107
6.4.3 Near Crack Tip Fields	109
6.5 Some Results under Cyclic Loading (Plastic Normality Condition)	123
6.5.1 Crack Tip Deformation	123
6.5.2 Plastic Zone Shape and Size	141
6.5.3 Near Crack Tip Fields	147
6.6 Some Results under Monotonic Loading ( Plastic Non-normality Condition)	158

6.6.1 Crack Tip Deformation	158
6.6.2 Near Crack Tip Fields	160
6.7 Concluding Remarks	170
<b>Chapter-7 Summary and Conclusion</b>	<b>171-175</b>
7.1 Introduction	171
7.2 Numerical Investigations	171
7.3 Recommended Future Work	173
<b>References</b>	<b>177</b>
<b>List of Publications</b>	<b>197</b>
<b>Appendix</b>	<b>199</b>

## LIST OF FIGURES

---

Figure No.	Caption	Page No.
Figure 2.1	Various basic loading modes in fracture mechanics (a) Opening mode (b) Sliding mode (c) Tearing mode	17
Figure 2.2	Coordinate system at a crack tip region	19
Figure 2.3	Crack tip opening displacement	25
Figure 2.4	Comparison of plane stress and plane strain plastic zone boundaries	29
Figure 3.1	Reference and deformed configurations	54
Figure 4.1	The typical definition of the hardening-softening-hardening flow stress function with the transition strains denoted by $\epsilon_1$ and $\epsilon_2$ and the slope of the three piece wise linear functions given by $h_1$ , $h_2$ and $h_3$ , respectively	71
Figure 5.1	The condensation of internal node in quadrilateral element comprised of four crossed constant strain triangular elements	82
Figure 5.2	Triangular finite element	83
Figure 5.3	Geometry used in the finite element simulation of small scale yielding with K-field boundary conditions; a) Full geometry and b) Portion of the geometry showing the crack tip.	86
Figure 5.4	Triangular finite element and it's representation in the local coordinate system	88
Figure 5.5	The variation of hardness function $g(\epsilon_p)$ with plastic strain $\epsilon_p$ .a) material B ( $h_2 = h_3 = 5.0$ ) and material C ( $h_2 = h_3 = 1.0$ ), b) material E ( $h_2 = -3.90$ , $h_3 = 15.0$ ) and material G	92



$$(h_2 = -3.90, h_3 = 15.0, \varepsilon_2 = 5.0)$$

Figure 6.1	Cyclic loading used in present fatigue crack simulation	98
Figure 6.1A	Typical mesh used in the finite element simulation (near tip mesh)	99
Figure 6.2	Crack-tip opening displacement $\delta_t (= b/b_0 - 1)$ versus applied $J$ -integral, $J_{app}$ in material B; a) 22 x 54 quadrilateral mesh, b) 22 x 64 quadrilateral mesh, c) 22 x 74 quadrilateral mesh	100-101
Figure 6.3	Plastic strain distribution for plastically compressible solid, material B, $\alpha_p = 0.28$ , a) 22 x 54 quadrilateral mesh, b) 22 x 64 quadrilateral mesh, c) 22 x 74 quadrilateral mesh	101-102
Figure 6.4	Stress distribution for a growing crack in material B, plastically incompressible, applied $J$ -integral, $J_{app}/(\sigma_0 b_0) = 2.25$	103
Figure 6.5	Curves of crack-tip opening displacement $(b/b_0 - 1)$ versus the applied $J$ -integral, $J_{app}$ for plastically incompressible and compressible hardening solid, a) Material B. b) Material C	104
Figure 6.6	Curves of crack-tip opening displacement $(b/b_0 - 1)$ versus the applied $J$ -integral, $J_{app}$ for plastically incompressible and compressible solids. a) Material E. b) Material G	105
Figure 6.7	Distribution of plastic strain, $\varepsilon_p$ , for material B with $J_{app}/(\sigma_0 b_0) = 2.25$ a) Plastically incompressible solid, $\alpha_p = 0.333333$ . b) Plastically compressible solid, $\alpha_p = 0.28$	108
Figure 6.8	Distribution of plastic strain, $\varepsilon_p$ , for material G with $J_{app}/(\sigma_0 b_0) = 2.25$ a) Plastically incompressible solid, $\alpha_p = 0.333333$ . b) Plastically compressible solid, $\alpha_p = 0.28$	108

Figure 6.9	Field distributions in the crack tip vicinity for material B (a hardening material) with $\alpha_p = 0.28$ at $J_{app}/(\sigma_0 b_0) = 2.25$ . a) Plastic strain, $\varepsilon_p$ b) Hydrostatic stress, $\sigma_h/\sigma_0$	110
Figure 6.10	Strain distributions in the crack tip vicinity for material E at $J_{app}/(\sigma_0 b_0) = 2.25$ . a) Distribution of $\varepsilon_p$ for a plastically incompressible solid, $\alpha_p = 0.333333$ . b) Distribution of $\varepsilon_p$ for a plastically compressible solid, $\alpha_p = 0.28$ . c) Distribution of $\varepsilon_{vol}$ for a plastically compressible solid, $\alpha_p = 0.28$	111-112
Figure 6.11	Distributions of normalized hydrostatic stress $\sigma_h/\sigma_0$ in the crack tip vicinity for material E at $J_{app}/(\sigma_0 b_0) = 2.25$ . a) Plastically incompressible solid, $\alpha_p = 0.333333$ . b) Plastically compressible solid, $\alpha_p = 0.28$	113
Figure 6.12	Distributions of normalized effective stress measures in the crack tip vicinity for material E at $J_{app}/(\sigma_0 b_0) = 2.25$ . a) $\sigma_e/\sigma_0$ for a plastically incompressible solid, $\alpha_p = 0.333333$ . b) $\sigma_e/\sigma_0$ for a plastically compressible solid, $\alpha_p = 0.28$ . c) $\sigma_M/\sigma_0$ for a plastically compressible solid, $\alpha_p = 0.28$	114-115
Figure 6.13	Distributions of plastic strain, $\varepsilon_p$ in the crack tip vicinity for material G at $J_{app}/(\sigma_0 b_0) = 2.25$ . a) Plastically incompressible solid, $\alpha_p = 0.333333$ . b) Plastically compressible solid, $\alpha_p = 0.28$ . c) Distribution of $\varepsilon_{vol}$ for a plastically compressible solid, $\alpha_p = 0.28$	117-118
Figure 6.14	Distributions of normalized hydrostatic stress $\sigma_h/\sigma_0$ in the crack tip vicinity for material G at $J_{app}/(\sigma_0 b_0) = 2.25$ . a) Plastically incompressible solid, $\alpha_p = 0.333333$ . b) Plastically compressible solid, $\alpha_p = 0.28$	119-120
Figure 6.15	Distributions of normalized effective stress measures in the	121-122

crack tip vicinity for material G at  $J_{app}/(\sigma_0 b_0) = 2.25$ . a)  $\sigma_e/\sigma_0$  for a plastically incompressible solid,  $\alpha_p = 0.333333$  .b)  $\sigma_e/\sigma_0$  for a plastically compressible solid,  $\alpha_p = 0.28$ . c)  $\sigma_M/\sigma_0$  for a plastically compressible solid,  $\alpha_p = 0.28$

- Figure 6.16 Crack-tip opening displacement  $\delta_t (= b/b_0 - 1)$  versus applied  $J$ -integral,  $J_{app}$  in material B with  $K_{max} = 0.5$  and  $K_{min} = 0$  ; a) Plastically incompressible solid b) Plastically compressible solid,  $\alpha_p = 0.28$  (up to 10<sup>th</sup> cycle) 125
- Figure 6.17 Crack-tip opening displacement  $\delta_t (= b/b_0 - 1)$  versus applied  $J$ -integral,  $J_{app}$  in material B with  $K_{max} = 1.0$  and  $K_{min} = 0$  ; a) Plastically incompressible solid b) Plastically compressible solid,  $\alpha_p = 0.28$  (up to 10<sup>th</sup> cycle) 125
- Figure 6.18 Crack-tip opening displacement  $\delta_t (= b/b_0 - 1)$  versus applied  $J$ -integral,  $J_{app}$  in material B with  $K_{max} = 1.5$  and  $K_{min} = 0.5$  ; a) Plastically incompressible solid b) Plastically compressible solid,  $\alpha_p = 0.28$  (up to 10<sup>th</sup> cycle) 126
- Figure 6.19 Crack-tip opening displacement  $\delta_t (= b/b_0 - 1)$  versus applied  $J$ -integral,  $J_{app}$  in material E with  $K_{max} = 0.5$  and  $K_{min} = 0$  ; a) Plastically incompressible solid b) Plastically compressible solid,  $\alpha_p = 0.28$  (up to 10<sup>th</sup> cycle) 126
- Figure 6.20 Crack-tip opening displacement  $\delta_t (= b/b_0 - 1)$  versus applied  $J$ -integral,  $J_{app}$  in material E with  $K_{max} = 1.0$  and  $K_{min} = 0$  ; a) Plastically incompressible solid b) Plastically compressible solid,  $\alpha_p = 0.28$  (up to 10<sup>th</sup> cycle) 127
- Figure 6.21 Crack-tip opening displacement  $\delta_t (= b/b_0 - 1)$  versus applied  $J$ -integral,  $J_{app}$  in material E with  $K_{max} = 1.5$  and  $K_{min} = 0.5$  ; a) Plastically incompressible solid b) Plastically compressible solid,  $\alpha_p = 0.28$  (up to 10<sup>th</sup> cycle) 127

Figure 6.22	Crack-tip opening displacement $\delta_t (= b/b_0 - 1)$ versus applied $J$ -integral, $J_{app}$ in material B with $K_{max} = 2.0$ and $K_{min} = 0$ ; a) Plastically incompressible solid b) Plastically compressible solid, $\alpha_p = 0.28$ , with overload, (up to 10 <sup>th</sup> cycle)	128
Figure 6.23	Crack-tip opening displacement $\delta_t (= b/b_0 - 1)$ versus applied $J$ -integral, $J_{app}$ in material E with $K_{max} = 2.0$ and $K_{min} = 0$ ; a) Plastically incompressible solid b) Plastically compressible solid, $\alpha_p = 0.28$ , with overload, (up to 10 <sup>th</sup> cycle)	129
Figure 6.24	Crack-tip deformations for plastically incompressible solid, material B, $K_{max} = 2.0$ and $K_{min} = 0$ ; a) At the end of loading phase, $K \rightarrow K_{max}$ b) At the end of unloading phase, $K \rightarrow K_{min}$ for 5 <sup>th</sup> cycle	131
Figure 6.25	Crack-tip deformations for plastically compressible solid, material B, $\alpha_p = 0.28$ , $K_{max} = 2.0$ and $K_{min} = 0$ ; a) At the end of loading phase, $K \rightarrow K_{max}$ b) At the end of unloading phase, $K \rightarrow K_{min}$ for 5 <sup>th</sup> cycle	132
Figure 6.26	Crack-tip deformations for plastically incompressible solid, material E, $K_{max} = 2.0$ and $K_{min} = 0$ ; a) At the end of loading phase, $K \rightarrow K_{max}$ b) At the end of unloading phase, $K \rightarrow K_{min}$ for 5 <sup>th</sup> cycle	133
Figure 6.27	Crack-tip deformations for plastically compressible solid, material E, $\alpha_p = 0.28$ , $K_{max} = 2.0$ and $K_{min} = 0$ ; a) At the end of loading phase, $K \rightarrow K_{max}$ b) At the end of unloading phase, $K \rightarrow K_{min}$ for 5 <sup>th</sup> cycle	134
Figure 6.28	Normalized crack extension ( $\Delta a/b_0$ ) versus normalized time ( $t/t_0$ ) in plastically incompressible and compressible solids,	136-137

material B; a)  $K_{\max} = 1.0$  and  $K_{\min} = 0$  b)  $K_{\max} = 2.0$  and  $K_{\min} = 0$  c)  $K_{\max} = 1.5$  and  $K_{\min} = 0.5$  d)  $K_{\max} = 2.0$  and  $K_{\min} = 1.0$

- Figure 6.29 Normalized crack extension ( $\Delta a/b_0$ ) versus normalized time ( $t/t_0$ ) in plastically incompressible and compressible solids, material E; a)  $K_{\max} = 1.0$  and  $K_{\min} = 0$  b)  $K_{\max} = 2.0$  and  $K_{\min} = 0$  c)  $K_{\max} = 1.5$  and  $K_{\min} = 0.5$  d)  $K_{\max} = 2.0$  and  $K_{\min} = 1.0$  137-138
- Figure 6.30 Normalized crack extension ( $\Delta a/b_0$ ) versus normalized time ( $t/t_0$ ) in plastically incompressible and compressible solids with overloading, material B; a)  $K_{\max} = 1.0$  and  $K_{\min} = 0$  b)  $K_{\max} = 2.0$  and  $K_{\min} = 0$  139
- Figure 6.31 Normalized crack extension ( $\Delta a/b_0$ ) versus normalized time ( $t/t_0$ ) in plastically incompressible and compressible solids with overloading, material E; a)  $K_{\max} = 1.0$  and  $K_{\min} = 0$  b)  $K_{\max} = 2.0$  and  $K_{\min} = 0$  139
- Figure 6.32 Fatigue crack growth  $da/dN$  versus  $\Delta K$  for plastically compressible solids,  $\alpha_p = 0.28$ , (a) Material B and (b) Material E, (with  $R=0$ ) at 5<sup>th</sup> cycle 140
- Figure 6.33 Distribution of plastic strain, for plastically incompressible solid, material B,  $K_{\max} = 1.0$  and  $K_{\min} = 0$ ; a) At the end of loading phase,  $K \rightarrow K_{\max}$  b) At the end of unloading phase,  $K \rightarrow K_{\min}$  for 10<sup>th</sup> cycle 142
- Figure 6.34 Distribution of plastic strain, for plastically compressible solid, material B,  $\alpha_p = 0.28$ ,  $K_{\max} = 1.0$  and  $K_{\min} = 0$ ; a) At the end of loading phase,  $K \rightarrow K_{\max}$  b) At the end of unloading 143

phase,  $K \rightarrow K_{\min}$  for 10<sup>th</sup> cycle

- Figure 6.35 Distribution of plastic strain, for plastically incompressible solid, material E,  $K_{\max} = 1.0$  and  $K_{\min} = 0$  ; a) At the end of loading phase,  $K \rightarrow K_{\max}$  b) At the end of unloading phase,  $K \rightarrow K_{\min}$  for 10<sup>th</sup> cycle 143
- Figure 6.36 Distribution of Plastic strain, for plastically compressible solid, material E,  $\alpha_p = 0.28$ ,  $K_{\max} = 1.0$  and  $K_{\min} = 0$  ; a) At the end of loading phase,  $K \rightarrow K_{\max}$  b) At the end of unloading phase,  $K \rightarrow K_{\min}$  for 10<sup>th</sup> cycle 144
- Figure 6.37 Distribution of plastic strain, for plastically incompressible solid, material B,  $K_{\max} = 1.0$  and  $K_{\min} = 0$  ; at the end of loading phase in 5<sup>th</sup> cycle a) With overload b) Without overload 145
- Figure 6.38 Distribution of plastic strain, for plastically compressible solid, material B,  $\alpha_p = 0.28$ ,  $K_{\max} = 1.0$  and  $K_{\min} = 0$  ; at the end of loading phase in 5<sup>th</sup> cycle a) With overload b) Without overload 145
- Figure 6.39 Distribution of plastic strain, for plastically incompressible solid, material E,  $K_{\max} = 1.0$  and  $K_{\min} = 0$  ; at the end of loading phase in 5<sup>th</sup> cycle a) With overload b) Without overload 146
- Figure 6.40 Distribution of plastic strain, for plastically compressible solid, material E,  $\alpha_p = 0.28$ ,  $K_{\max} = 1.0$  and  $K_{\min} = 0$  ; at the end of loading phase in 5<sup>th</sup> cycle a) With overload b) Without overload 146
- Figure 6.41 Plastic strain distribution for plastically compressible solid, material B,  $\alpha_p = 0.28$ , a)  $K_{\max} = 0.5$  and  $K_{\min} = 0$  b)  $K_{\max} = 1.0$  and  $K_{\min} = 0$  c)  $K_{\max} = 1.5$  and  $K_{\min} = 0.5$  ; at the end of loading phase for 10<sup>th</sup> cycle 148-149

Figure 6.42	Plastic strain distribution for plastically compressible solid, material E, $\alpha_p = 0.28$ , a) $K_{\max} = 0.5$ and $K_{\min} = 0$ b) $K_{\max} = 1.0$ and $K_{\min} = 0$ c) $K_{\max} = 1.5$ and $K_{\min} = 0.5$ ; at the end of loading phase for 10 <sup>th</sup> cycle	149-150
Figure 6.43	Hydrostatic stress for plastically incompressible solid, material B, $K_{\max} = 1.0$ and $K_{\min} = 0$ ; a) At the end of loading phase b) At the end of unloading phase for 10 <sup>th</sup> cycle	152
Figure 6.44	Hydrostatic stress for plastically compressible solid, $\alpha_p = 0.28$ , material B, $K_{\max} = 1.0$ and $K_{\min} = 0$ ; a) At the end of loading phase b) At the end of unloading phase for 10 <sup>th</sup> cycle	153
Figure 6.45	Hydrostatic stress for plastically incompressible solid, material E, $K_{\max} = 1.0$ and $K_{\min} = 0$ ; a) At the end of loading phase b) At the end of unloading phase for 10 <sup>th</sup> cycle	154
Figure 6.46	Hydrostatic stress for plastically compressible solid, $\alpha_p = 0.28$ , material E, $K_{\max} = 1.0$ and $K_{\min} = 0$ ; a) At the end of loading phase b) At the end of unloading phase for 10 <sup>th</sup> cycle	155
Figure 6.47	Distributions of normalized effective stress measures for plastically compressible solid, $\alpha_p = 0.28$ , material B, $K_{\max} = 1.0$ and $K_{\min} = 0$ ; a) At the end of loading phase b) At the end of unloading phase for 10 <sup>th</sup> cycle	156
Figure 6.48	Distributions of normalized effective stress measures for plastically compressible solid, $\alpha_p = 0.28$ , material E, $K_{\max} = 1.0$ and $K_{\min} = 0$ ; a) At the end of loading phase b) At the end of unloading phase for 10 <sup>th</sup> cycle	157
Figure 6.49	Crack-tip opening displacement $\delta_t (= b/b_0 - 1)$ versus applied $J$ -integral, $J_{\text{app}} \cdot J_{\text{app}} / (\sigma_0 b_0) = 2.25$ a) Material B, b) Material	159-160

E, plastically incompressible and compressible conditions ( $\alpha_p = \beta_p = 0.28$ ), c) Material E, plastically incompressible and compressible conditions ( $\alpha_p = 0.28$  &  $\beta_p = 0.20$ )

- Figure 6.50 Distribution of accumulated plastic strain  $\epsilon_p$  at the crack tip of material B,  $J_{app}/(\sigma_0 b_0) = 2.25$ . a) Plastically incompressible, b) Plastically compressible ( $\alpha_p = \beta_p = 0.28$ ), c) plastically compressible ( $\alpha_p = 0.28$  &  $\beta_p = 0.20$ ) 161-162
- Figure 6.51 Distribution of accumulated plastic strain  $\epsilon_p$  at the crack tip of material E,  $J_{app}/(\sigma_0 b_0) = 2.25$ . a) Plastically incompressible, b) Plastically compressible ( $\alpha_p = \beta_p = 0.28$ ), c) plastically compressible ( $\alpha_p = 0.28$  &  $\beta_p = 0.20$ ) 163-164
- Figure 6.52 Distribution of volumetric strain  $\epsilon_{vol}$  at the crack tip,  $J_{app}/(\sigma_0 b_0) = 2.25$ . material E a)  $\alpha_p = 0.28$  &  $\beta_p = 0.20$  b)  $\alpha_p = \beta_p = 0.28$  165
- Figure 6.53 Normalized hydrostatic stress distribution at the crack tip vicinity for material E,  $J_{app}/(\sigma_0 b_0) = 2.25$ . a) Plastically incompressible, b) Plastically compressible ( $\alpha_p = \beta_p = 0.28$ ), c) Plastically compressible ( $\alpha_p = 0.28$  &  $\beta_p = 0.20$ ) 167-168
- Figure 6.54 Effective stress distribution at the crack tip vicinity for material E,  $J_{app}/(\sigma_0 b_0) = 2.25$ . a) Plastically compressible ( $\alpha_p = \beta_p = 0.28$ ), b) Plastically compressible ( $\alpha_p = 0.28$  &  $\beta_p = 0.20$ ) 169



## LIST OF ABBREVIATIONS AND SYMBOLS

---

FEM	Finite Element Method
BEM	Boundary Element Method
LEFM	Elastic Fracture Mechanic
EPFM	Elastic Plastic Fracture Mechanics
CTOD	Crack Tip Opening Displacement
VACNT	Vertically Aligned Carbon Nano Tube
PFM	Probabilistic fracture mechanics
SSY	Small Scale Yielding
HRR	Hutchinson, Rice and Rosengren
X-FEM	Extended Finite Element Method
CZM	Cohesive Zone Model
FDM	Finite Difference Method
$\sigma_{ij}$	Stress Tensor
$\sigma_{xx}, \sigma_{yy}, \sigma_{zz}$	Stress Components in x, y and z direction
$\nu$	Poisson ratio
$\mu$	Shear modulus
$K$	Stress Intensity Factor
$r_t$	Radius
$u_{xx}, u_{yy}, u_{zz}$	Displacement in x, y and z direction
$K_{IC}$	Mode I Critical Stress Intensity Factor
$U$	Potential Energy
$V$	Volume of the Body
$W$	Strain Energy Density
$S_t$	Part of the body Subjected to Traction
$E$	Young's Modulus
$G$	Energy Release Rate

$\Gamma$	Contour Enclosing the Crack Tip
$n$	Unit Outward Normal on $\Gamma$
$\bar{T}$	Surface Traction
$T_i$	Traction Vector
$r_y$	Irwin Plastic Zone Correction
$d$	Crack Tip Opening Displacement
$a$	Half Crack Length
$J_{app}$	Applied $J$ integral
$F_{ij}$	Deformation Gradient
$e_{ij}$	Eulerian Strain Tensor
$D_{ij}$	Deformation Tensor
$L_{ij}$	Velocity Gradient
$W_{ij}$	Velocity tensor or spin tensor
$\rho$	Density
$\hat{\tau}_{ij}$	Jaumann rate of Kirchhoff stress
$\dot{\epsilon}_p$	Plastic Strain Rate
$\sigma_e$	Effective Equivalent Stress
$\delta_{ij}$	Kronecker Delta
$p_{ij}$	Deviatoric Kirchhoff Plastic Stress Tensor
$L_{ijkl}$	Tensor of elastic Moduli
$\dot{\epsilon}_0$	Reference Strain Rate
$m$	Rate Hardening Exponent
$\sigma_0$	Reference Stress
$\alpha_p$	Plastic Compressibility

Symbols not listed here, are defined as they appear in text.