

Contents

Abstract	v
List of Figures	ix
1 Introduction	1
1.1 Literature Review	2
1.2 The Non-Differentiability Constraints in Control	6
1.3 The Fractional Calculus	7
1.4 The Regularization Approach	12
1.5 The Equivalent Control Method	13
1.6 Motivation	15
1.7 Organization of the Thesis	16
1.8 Summary	17
2 Non-Differentiable Function Tracking	19
2.1 Introduction	19
2.2 Motivation	20
2.3 The Tracking Problem	20
2.4 The Switch-Controlled RL Circuit: A Case Study	21
2.5 Tracking of Constant and Smooth Reference Functions	22
2.6 The Fractional Calculus Approach to Tracking Problem	24
2.7 General Class of Nonlinear Systems Affine in Control	29
2.8 Illustrative Example	31
2.9 Summary	32

3	Differentiator Design under Non-Differentiability	35
3.1	Introduction	35
3.2	Motivation	37
3.3	Notations	37
3.4	Problem Formulation	38
3.5	Fractional-Order Differentiator	38
3.6	Discretization of Fractional-Order Differential Equations	39
3.7	Implicit Euler Discretization	40
3.8	Illustrative Example	47
3.9	Summary	49
4	Fractional-Order Sliding Mode Control under Uncertainty	51
4.1	Introduction	51
4.2	Motivation	53
4.3	Fractional-Order Sliding Mode Control	53
4.4	Extension of Lyapunov's Theory to Fractional-Order Systems	55
4.5	Main Results	57
4.6	Illustrative Example	61
4.7	Summary	63
5	Conclusions and Future Scope	65
5.1	Conclusions	65
5.2	Contribution	66
5.3	Future Scope	66